

A Static Verification Framework for Message Passing in Go using Behavioural Types

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The Go Programming Language

- Developed at Google for multicore programming
- Statically typed, natively compiled, **concurrent**
- Channel-based message passing for concurrency
- Used by major technology companies, e.g.



UBER



NETFLIX

Go and concurrency

Approach and philosophy

*Do not communicate by sharing memory;
Instead, share memory by communicating*
— Go language proverb

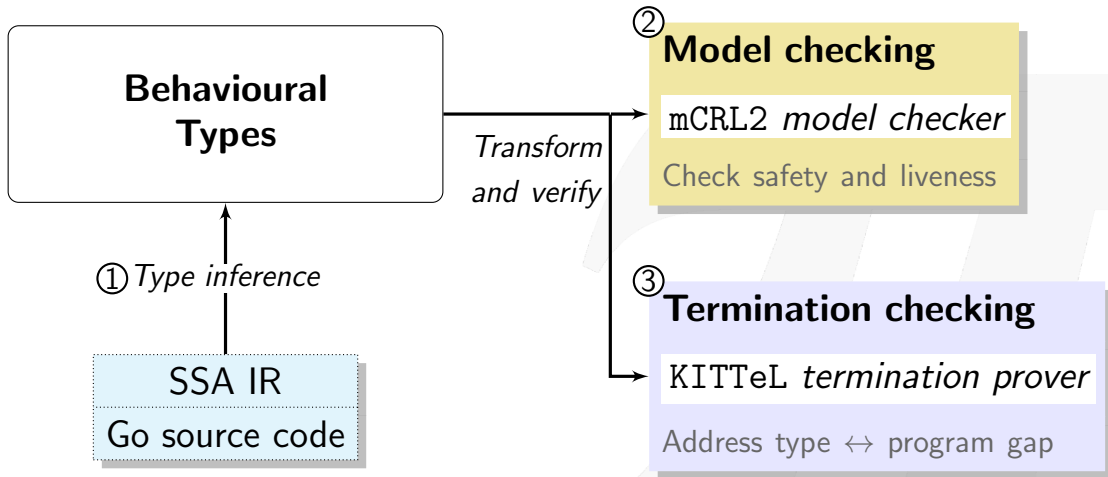
Encourages message passing over locking

- **Goroutines:** lightweight threads
- **Channels:** typed FIFO queues

Inspired by Hoare's CSP/**process calculi**

Static verification framework for Go

Overview



Concurrency in Go

Goroutines

```
1 func main() {  
2     ch := make(chan string)  
3     go send(ch)  
4     print(<-ch)  
5     close(ch)  
6 }  
7  
8 func send(ch chan string) {  
9     ch <- "Hej ICSE!"  
10 }
```

go keyword + function call

- Spawns function as goroutine
- Runs in parallel to parent

Concurrency in Go

Channels

```

1 func main() {
2   ch := make(chan string)
3   go send(ch)
4   print(<-ch)
5   close(ch)
6 }
7
8 func send(ch chan string) {
9   ch <- "Hej ICSE!"
10 }

```

Create **new** channel

- Synchronous by default

Receive from channel

Close a channel

- No more values sent to it
- Can only close once

Send to channel

Concurrency in Go

Channels

```
1 func main() {
2     ch := make(chan string)
3     go send(ch)
4     print(<-ch)
5     close(ch)
6 }
7
8 func send(ch chan string) {
9     ch <- "Hej ICSE!"
10 }
```

Also `select-case`:

- Wait on multiple channel operations
- `switch-case` for communication

Concurrency in Go

Deadlock detection

```

1 func main() {
2     ch := make(chan string)
3     go send(ch)
4     print(<-ch)
5     close(ch)
6 }
7
8 func send(ch chan string) {
9     ch <- "Hej ICSE!"
10 }

```

- Send message thru channel
- Print message on screen

Output:

```

$ go run hello.go
Hej ICSE!
$

```


Concurrency in Go

Deadlock detection

Missing 'go' keyword

```

1 // import _ "net"
2 func main() {
3     ch := make(chan string)
4     send(ch) // Oops
5     print(<-ch)
6     close(ch)
7 }
8
9 func send(ch chan string) {
10     ch <- "Hej ICSE"
11 }

```

- Only one (main) goroutine
- Send without receive - blocks

Output:

```

$ go run deadlock.go
fatal error: all goroutines
are asleep - deadlock!
$

```

Concurrency in Go

Deadlock detection

Missing 'go' keyword

```

1 // import _ "net"
2 func main() {
3     ch := make(chan string)
4     send(ch) // Oops
5     print(<-ch)
6     close(ch)
7 }
8
9 func send(ch chan string) {
10     ch <- "Hej ICSE"
11 }

```

Go's runtime deadlock detector

- Checks if **all** goroutines are blocked ('global' deadlock)
- Print message then crash
- Some packages disable it (e.g. net)

Concurrency in Go

Deadlock detection

Missing 'go' keyword

```

1  import _ "net" // unused
2  func main() {
3      ch := make(chan string)
4      send(ch) // Oops
5      print(<-ch)
6      close(ch)
7  }
8
9  func send(ch chan string) {
10     ch <- "Hej ICSE"
11 }

```

Import unused, unrelated package

Concurrency in Go

Deadlock detection

Missing 'go' keyword

```

1  import _ "net" // unused
2  func main() {
3      ch := make(chan string)
4      send(ch) // Oops
5      print(<-ch)
6      close(ch)
7  }
8
9  func send(ch chan string) {
10     ch <- "Hej ICSE"
11 }

```

- Only one (main) goroutine
- Send without receive - blocks

Output:

```
$ go run deadlock2.go
```

Hangs: Deadlock **NOT** detected

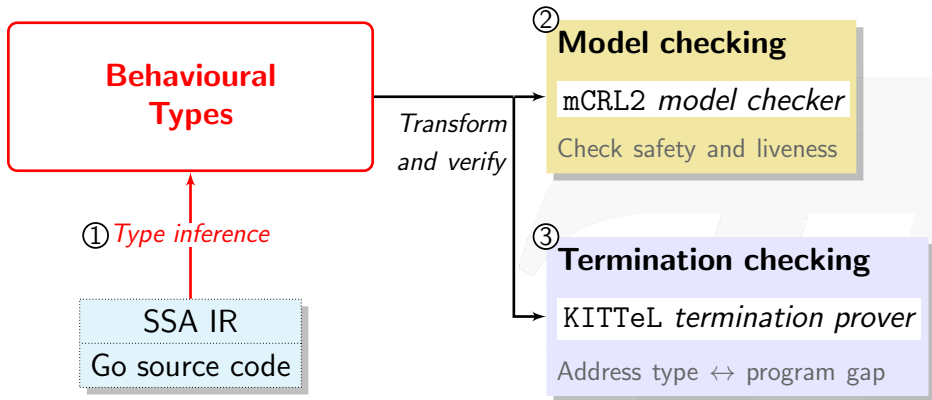
Our goal

Check liveness/safety properties **in addition to** global deadlocks

- Apply process calculi techniques to Go
- Use model checking to statically analyse Go programs

Behavioural type inference

Abstract Go communication as Behavioural Types



Infer Behavioural Types from Go Program

Go source code

```

1 func main() {
2     ch := make(chan int)
3     go send(ch)
4     print(<-ch)
5     close(ch)
6 }
7
8 func send(c chan int) {
9     c <- 1
10 }

```

Behavioural Types

Types of CCS-like [Milner '80]
process calculus

- Send/Receive
- new (channel)
- parallel composition (spawn)

Go-specific

- Close channel
- Select (guarded choice)

Infer Behavioural Types from Go Program

Go source code

```

1 func main() {
2   ch := make(chan int)
3   go send(ch)
4   print(<-ch)
5   close(ch)
6 }
7
8 func send(c chan int) {
9   c <- 1
10 }

```

Inferred Behavioural Types

→

$$\left\{ \begin{array}{l} \text{main()} = (\text{new } ch); \\ \quad (\text{send}\langle ch \rangle \mid \\ \quad \quad ch; \\ \quad \quad \text{close } ch), \\ \text{send}(ch) = \overline{ch} \end{array} \right\}$$

Infer Behavioural Types from Go Program

Go source code

```

1 func main() {
2   ch := make(chan int)
3   go send(ch)
4   print(<-ch)
5   close(ch)
6 }
7
8 func send(c chan int) {
9   c <- 1
10 }
    
```

Inferred Behavioural Types

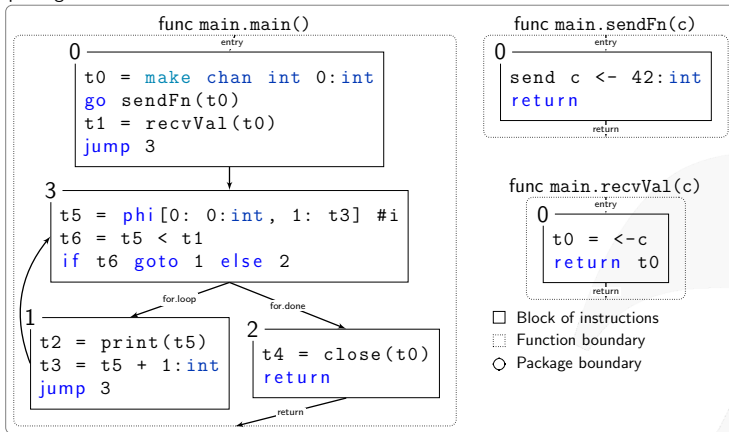
~~create channel~~ → `main() = (new ch);`
~~spawn~~ → `(send⟨ch⟩ |`
~~receive~~ → `ch;`
~~close~~ → `close ch),`
`send(ch) = $\bar{c}h$`

Infer Behavioural Types from Go Program

```
1 func main() {
2     ch := make(chan int) // Create channel
3     go sendFn(ch)        // Run as goroutine
4     x := recvVal(ch)     // Function call
5     for i := 0; i < x; i++ {
6         print(i)
7     }
8     close(ch) // Close channel
9 }
10 func sendFn(c chan int) { c <- 3 } // Send to c
11 func recvVal(c chan int) int { return <-c } // Recv from c
```

Infer Behavioural Types from Go Program

package main



Analyse in

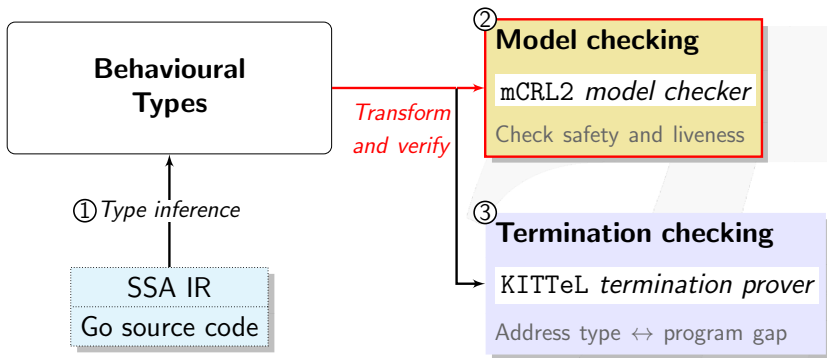
Static **S**ingle
Assignment

SSA representation
of input program

- Only inspect **communication** primitives
- Distinguish between unique channels

Model checking behavioural types

From behavioural types to **model** and **property specification**



Model checking behavioural types

$$M \models \phi$$

- **LTS model** : inferred type + type semantics
 - **Safety/liveness properties** : μ -calculus formulae for LTS
 - Check with mCRL2 model checker
 - mCRL2 constraint: *Finite control* (no spawning in loops)
- Global deadlock freedom
 - Channel safety (no send/`close` on closed channel)
 - Liveness (partial deadlock freedom)
 - Eventual reception

Behavioural Types as LTS model

Standard CCS semantics, i.e.

$$\begin{array}{ccc}
 \bar{a}; T \xrightarrow{\bar{a}} T & \frac{T \xrightarrow{\bar{a}} T' \quad S \xrightarrow{a} S'}{T \mid S \xrightarrow{\tau_a} T' \mid S'} & a; T \xrightarrow{a} T \\
 \text{Send on channel } a & \text{Synchronise on } a & \text{Receive on channel } a
 \end{array}$$

Behavioural Types as LTS model

Standard CCS semantics, i.e.

$$\begin{array}{c}
 \bar{a}; T \xrightarrow{\bar{a}} T \\
 \text{Send on channel } a
 \end{array}
 \quad
 \frac{T \xrightarrow{\bar{a}} T' \quad S \xrightarrow{a} S'}{T \mid S \xrightarrow{\tau_a} T' \mid S'}
 \quad
 \begin{array}{c}
 a; T \xrightarrow{a} T \\
 \text{Receive on channel } a
 \end{array}$$

Synchronise on a

Specifying properties of model

Barbs (predicates at each state) describe property at state

- Concept from process calculi [Milner '88, Sangiorgi '92]
- μ -calculus **properties** specified in terms of barbs

Barbs ($T \downarrow_o$)

- Predicates of state/type T
- Holds when T is ready to fire action o

Specifying properties of model

$$\begin{array}{ccc}
 \bar{a}; T \downarrow_{\bar{a}} & \frac{T \downarrow_{\bar{a}} \quad T' \downarrow_a}{T \mid T' \downarrow_{\tau_a}} & a; T \downarrow_a \\
 \text{Ready to send} & \text{Ready to synchronise} & \text{Ready to receive}
 \end{array}$$

Barbs ($T \downarrow_o$)

- Predicates of state/type T
- Holds when T is ready to fire action o

Specifying properties of model

$$\begin{array}{ccc}
 \bar{a}; T \downarrow_{\bar{a}} & \frac{T \downarrow_{\bar{a}} \quad T' \downarrow_a}{T \mid T' \downarrow_{\tau_a}} & a; T \downarrow_a \\
 \text{Ready to send} & \text{Ready to synchronise} & \text{Ready to receive}
 \end{array}$$

Barbs ($T \downarrow_o$)

- Predicates of state/type T
- Holds when T is ready to fire action o

Specifying **properties** of model

Given

- **LTS model** from inferred behavioural types
- **Barbs** of the LTS model

Express **safety/liveness properties**

- As μ -calculus formulae
 - In terms of the **model** and the **barbs**
- Global deadlock freedom
 - Channel safety (no send/`close` on closed channel)
 - Liveness (partial deadlock freedom)
 - Eventual reception

Property: Liveness (partial deadlock freedom)

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \text{eventually} (\langle \tau_a \rangle \text{true}))$$

\mathcal{A} = set of initialised channels

If a channel is ready to **receive** or **send**,
then **eventually**
it can synchronise (τ_a)

(i.e. there's corresponding send for **receiver**/recv for **sender**)

Property: Liveness (partial deadlock freedom)

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \text{eventually} (\langle \tau_a \rangle \text{true}))$$

where:

$$\text{eventually} (\phi) \stackrel{\text{def}}{=} \mu \mathbf{y}. (\phi \vee \langle \mathbb{A} \rangle \mathbf{y})$$

If a channel is ready to **receive** or **send**,
 then **for some reachable state**
 it can synchronise (τ_a)

Property: Liveness (partial deadlock freedom)

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \text{eventually} (\langle \tau_a \rangle \text{true}))$$

```

1 func main() {
2     ch := make(chan int)
3     go looper() // !!!
4     <-ch       // No matching send
5 }
6 func looper() {
7     for {
8     }
9 }

```

✗ Runtime detector:
Hangs

✓ Our tool: NOT live

Property: Liveness (partial deadlock freedom)

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \text{eventually} (\langle \tau_a \rangle \text{true}))$$

```

1 func main() {
2     ch := make(chan int)
3     go loopSend(ch)
4     <-ch
5 }
6 func loopSend(ch chan int) {
7     for i := 0; i < 10; i-- {
8         // Does not terminate
9     }
10    ch <- 1
11 }

```

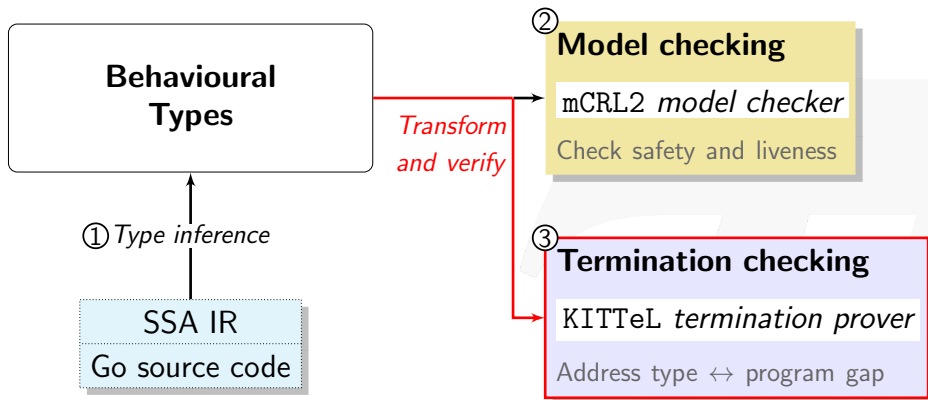
What about this one?

- Type: **Live**
- Program: **NOT** live

Needs **additional** guarantees

Termination checking

Addressing the program-type *abstraction gap*



Termination checking with KITTeL

Type inference does not consider *program data*

- Type liveness \neq Program liveness if program non-terminating
 - Especially when involving iteration
- ⇒ Check for loop termination
- If terminates, type liveness = program liveness

	Program terminates	Program does not terminate
Type live	✓ Program live	?
Type not live	✗ Program not live	✗ Program not live

Tool: Godel-Checker

The screenshot shows the Godel-Checker web interface. The top part displays Go source code for a program with a deadlock. The code is as follows:

```

1 package main
2
3 import "fmt"
4
5 //import _ "net" // Load "net" package
6
7 func main() {
8     ch := make(chan int) // Create channel.
9     send(ch)             // spawn as goroutine.
10    print(<-ch)          // Recv from channel.
11 }
12
13 func send(ch chan int) { // Channel as parameter.
14     fmt.Println("Waiting to send...")
15     ch <- 1 // Send to channel.
16     fmt.Println("Sent")
17 }
18

```

Below the code, there are buttons for "Show MiGo Type", "Show SSA", "2-deadlock", and "Load". The "2-deadlock" button is selected. A message below the buttons says "Last operation completed in 2.015834798s".

The middle part of the interface shows a terminal window with the following output:

```

Waiting to send...
Fatal error: all goroutines are asleep - deadlock!
goroutine 1 [chan send]:
main.send(0xc4200a0000)
    /tmp/compile8.go:15 +0x7b
main.main()
    /tmp/compile8.go:9 +0x49
Program exited: exit status 2

```

At the bottom right, there is a "Model check" button and a "Close" button. A summary of model checking results is shown in a dark box:

```

File: godel67839927
Finite Control: True
No terminal state: False
No global deadlock: False
Liveness: True
Safety: True
Eventual reception: True

```

<https://github.com/nickng/gospal>

<https://bitbucket.org/MobilityReadingGroup/godel-checker>



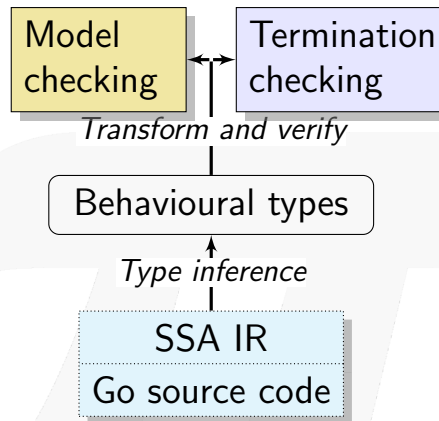
 Understanding Concurrency with Behavioural Types

GolangUK Conference 2017

Conclusion

Verification framework based on
Behavioural Types

- Behavioural types for Go concurrency
- Infer types from Go source code
- Model check types for safety/liveness
- + termination for iterative Go code



In the paper

See our paper for omitted topics in this talk:

- Behavioural type inference algorithm
- Treatment of buffered (asynchronous) channels
- The `select` (non-deterministic choice) primitive
- Definitions of behavioural type semantics/barbs

Table 3: Go programs verified by our framework and comparison with existing static deadlock detection tools.

Programs	LoC	# states	Godel Checker							dingo-hunter [36]		gopherlyzer [40]		GolInfer/Gong [30]			
			ψ_g	ψ_l	ψ_s	ψ_e	Infer	Live	Live+CS	Term	Live	Time	DF	Time	Live	CS	Time
1 mismatch [36]	29	53	×	×	✓	✓	620.7	996.8	996.7	✓	×	639.4	×	3956.4	×	✓	616.8
2 fixed [36]	27	16	✓	✓	✓	✓	624.4	996.5	996.3	✓	✓	603.1	✓	3166.3	✓	✓	601.0
3 fanin [36, 39]	41	39	✓	✓	✓	✓	631.1	996.2	996.2	✓	✓	608.9	✓	19.8	✓	✓	696.7
4 sieve [30, 36]	43	∞			n/a		-	-	-	n/a	n/a	-	n/a	-	✓	✓	778.3
5 philo [40]	41	65	×	×	✓	✓	6.1	996.5	996.6	✓	×	34.2	×	27.0	×	✓	16.8
6 dinephil3 [13, 33]	55	3838	✓	✓	✓	✓	645.2	996.4	996.3	✓	n/a	-	n/a	-	✓	✓	13.2 min
7 starvephil3	47	3151	×	×	✓	✓	628.2	996.5	996.5	✓	n/a	-	n/a	-	×	✓	3.5 min
8 sel [40]	22	103	×	×	✓	✓	4.2	996.7	996.6	✓	×	15.3	×	13.0	×	✓	50.5
9 selFixed [40]	22	20	✓	✓	✓	✓	4.0	996.3	996.4	✓	✓	14.9	✓	3168.3	✓	✓	13.1
10 jobsched [30]	43	43	✓	✓	✓	✓	632.7	996.7	1996.1	✓	n/a	-	✓	4753.6	✓	✓	635.2
11 forselect [30]	42	26	✓	✓	✓	✓	623.3	996.4	996.3	✓	✓	611.8	n/a	-	✓	✓	618.6
12 cond-recur [30]	37	12	✓	✓	✓	✓	4.0	996.2	996.2	✓	✓	9.4	n/a	-	✓	✓	14.7
13 concsys [42]	118	15	×	×	✓	✓	549.7	996.5	996.4	✓	n/a	-	×	5278.6	×	✓	521.3
14 alt-bit [30, 35]	70	112	✓	✓	✓	✓	634.4	996.3	996.3	✓	n/a	-	n/a	-	✓	✓	916.8
15 prod-cons	28	106	✓	×	✓	✓	4.1	996.4	1996.2	✓	×	10.1	×	30.1	×	✓	21.8
16 nonlive	16	8	✓	✓	✓	✓	630.1	996.6	996.5	timeout	⊗	613.6	n/a	-	⊗	×	613.8
17 double-close	15	17	✓	✓	×	✓	3.5	996.6	1996.6	✓	⊗	8.7	⊗	11.8	✓	×	9.1
18 stuckmsg	8	4	✓	✓	✓	×	3.5	996.6	996.6	✓	n/a	-	n/a	-	✓	✓	7.6

Future and related work

Extend framework to support more safety properties

Different verification approaches

- Godel-Checker model checking [ICSE'18] (this talk)
- Gong type verifier [POPL'17]
- Choreography synthesis [CC'15]

Different concurrency issues (e.g. data races)





Property: Global deadlock freedom

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \langle \mathbb{A} \rangle \text{true})$$

```
1 import _ "net" // unused
2 func main() {
3     ch := make(chan string)
4     send(ch) // Oops
5     print(<-ch)
6     close(ch)
7 }
8
9 func send(ch chan string) {
10     ch <- "Hej ICSE"
11 }
```

- Send ($\downarrow_{\bar{ch}}$: line 10)
- No synchronisation
- No more reduction

Property: Global deadlock freedom

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \langle \mathbb{A} \rangle \text{true})$$

If a channel a is ready to **receive** or **send**,
then there must be a **next state** (i.e. not stuck)

\mathcal{A} = set of all initialised channels

\mathbb{A} = set of all labels

Property: Global deadlock freedom

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_a \vee \downarrow_{\bar{a}} \implies \langle \mathbb{A} \rangle \text{true})$$

If a channel a is ready to **receive** or **send**,
then there must be a **next state** (i.e. not stuck)

\mathcal{A} = set of all initialised channels \mathbb{A} = set of all labels
 \implies Ready **receive/send** = not end of program.

Property: Channel safety

$$\bigwedge_{a \in \mathcal{A}} (\downarrow a^* \implies \neg(\downarrow \bar{a} \vee \downarrow \text{clo } a))$$

```
1 func main() {
2     ch := make(chan int)
3     go func(ch chan int) {
4         ch <- 1 // is ch closed?
5     }(ch)
6     close(ch)
7     <-ch
8 }
```

Property: Channel safety

$$\bigwedge_{a \in \mathcal{A}} (\downarrow a^* \implies \neg(\downarrow \bar{a} \vee \downarrow \text{clo } a))$$

```
1 func main() {
2   ch := make(chan int)
3   go func(ch chan int) {
4     ch <- 1 // is ch closed?
5   }(ch)
6   close(ch)
7   <-ch
8 }
```

- $\downarrow \text{clo } ch$ when `close(ch)`
- $\downarrow ch^*$ fires after closed
- Send ($\downarrow \bar{ch}$: line 4)

Property: Channel safety

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_{a^*} \implies \neg(\downarrow_{\bar{a}} \vee \downarrow_{\text{clo } a}))$$

Once a channel a is closed (a^*),
it will not be **sent to**, nor closed again (**clo** a)

Property: Liveness (select)

$$\bigwedge_{\tilde{a} \in \mathcal{P}(\mathcal{A})} (\downarrow_{\tilde{a}} \implies \text{eventually} (\langle \{\tau_a \mid a \in \tilde{a}\} \rangle \text{true}))$$

“If one of the channels in `select` is ready to `receive` or `send`,
Then **eventually** it will synchronise (τ_a)

(i.e. there's corresponding send for `receiver`/recv for `sender`)

Property: Eventual reception

$$\bigwedge_{a \in \mathcal{A}} (\downarrow_{a^\bullet} \implies \text{eventually } (\langle \tau_a \rangle \text{true}))$$

“If an item is sent to a buffered channel (a^\bullet),
Then **eventually** it will be consumed/synchronised (τ_a)

(i.e. no orphan messages)

Behavioural Types for Go

Type syntax

$$\begin{aligned}\alpha &:= \bar{u} \mid u \mid \tau \\ T, S &:= \alpha; T \mid T \oplus S \mid \&\{\alpha_i; T_i\}_{i \in I} \mid (T \mid S) \mid \mathbf{0} \\ &\mid (\mathbf{new} \ a)T \mid \mathbf{close} \ u; T \mid \mathbf{t}\langle \tilde{u} \rangle \mid [u]_k^n \mid \mathit{buf}[u]_{\mathit{closed}} \\ \mathbf{T} &:= \{\mathbf{t}(\tilde{y}_i) = T_i\}_{i \in I} \mathbf{in} \ S\end{aligned}$$

- Types of a CCS-like process calculus
- Abstracts Go concurrency primitives
 - Send/Recv, new (channel), parallel composition (spawn)
 - Go-specific: Close channel, Select (guarded choice)